



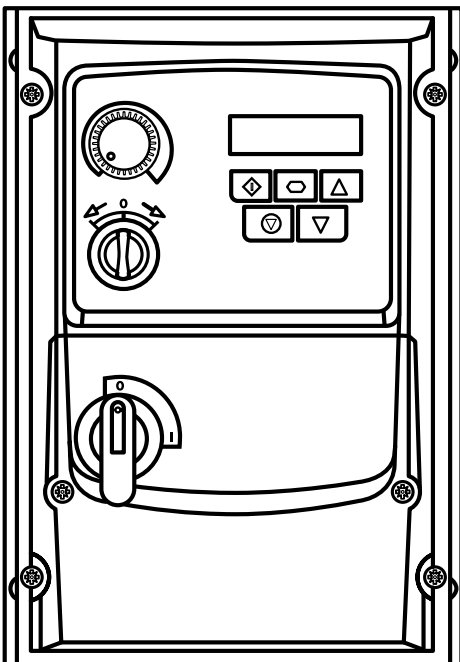
OPTIDRIVE™

Single Phase Output

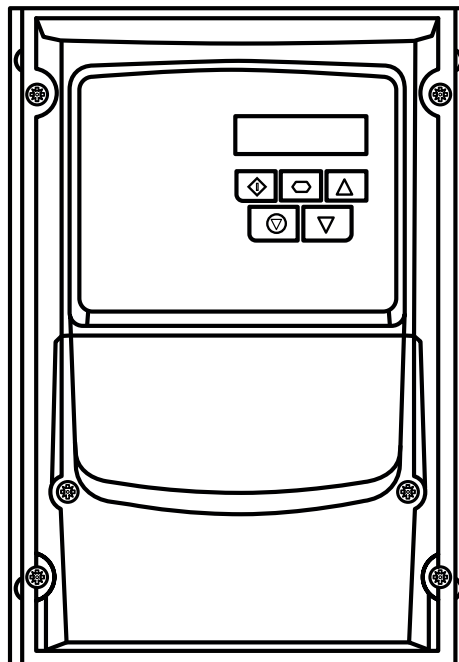
IP66 (NEMA 4X)

0.37 – 1.1kW / 0.5 – 1.5HP
110 – 230V

Switched



Non-switched



- 1 CHECK:** Check the correct drive type, check suitable motor type & info
- 2 PREPARE:** Correct tools, suitable mounting location, weather protection
- 3 MOUNT:** Mechanical mounting
- 4 CONNECT:** Power & Control connections
- 5 CHECK:** Final check of everything before operation
- 6 POWER ON**
- 7 COMMISSION** the drive parameters
- 8 OPERATE** and check everything is as intended



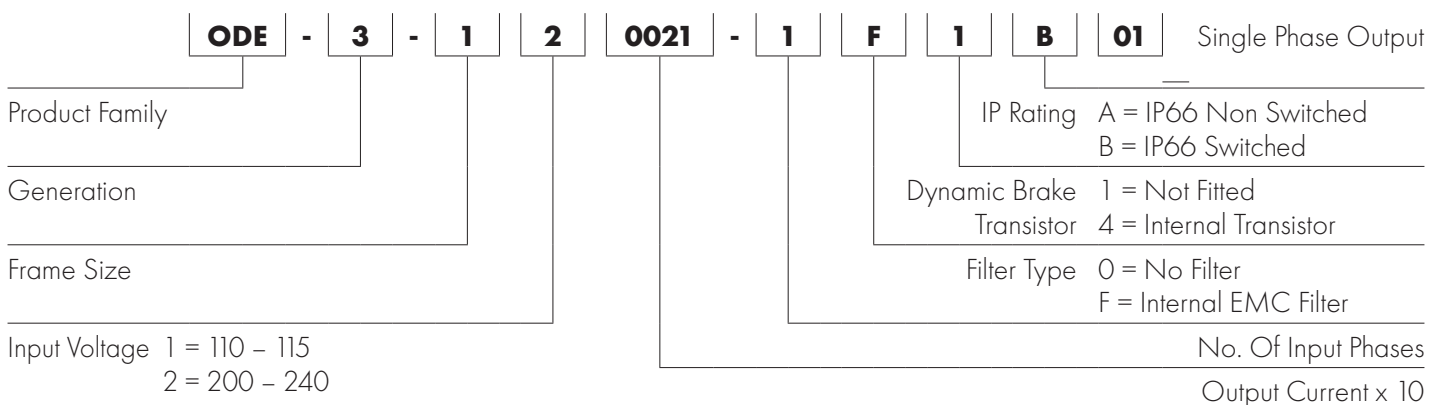
WARNING! The Optidrive should ONLY be installed by a qualified electrician.

NOTE This guide does not provide detailed installation, safety or operational instructions. See the Optidrive E3 IP66 Outdoor User Manual for complete information. Unpack and check the drive. Notify the supplier and shipper immediately of any damage.

1 CHECK

Identifying the Drive by Model Number

Each drive can be identified by its model number, as shown in the table below.



2 PREPARE

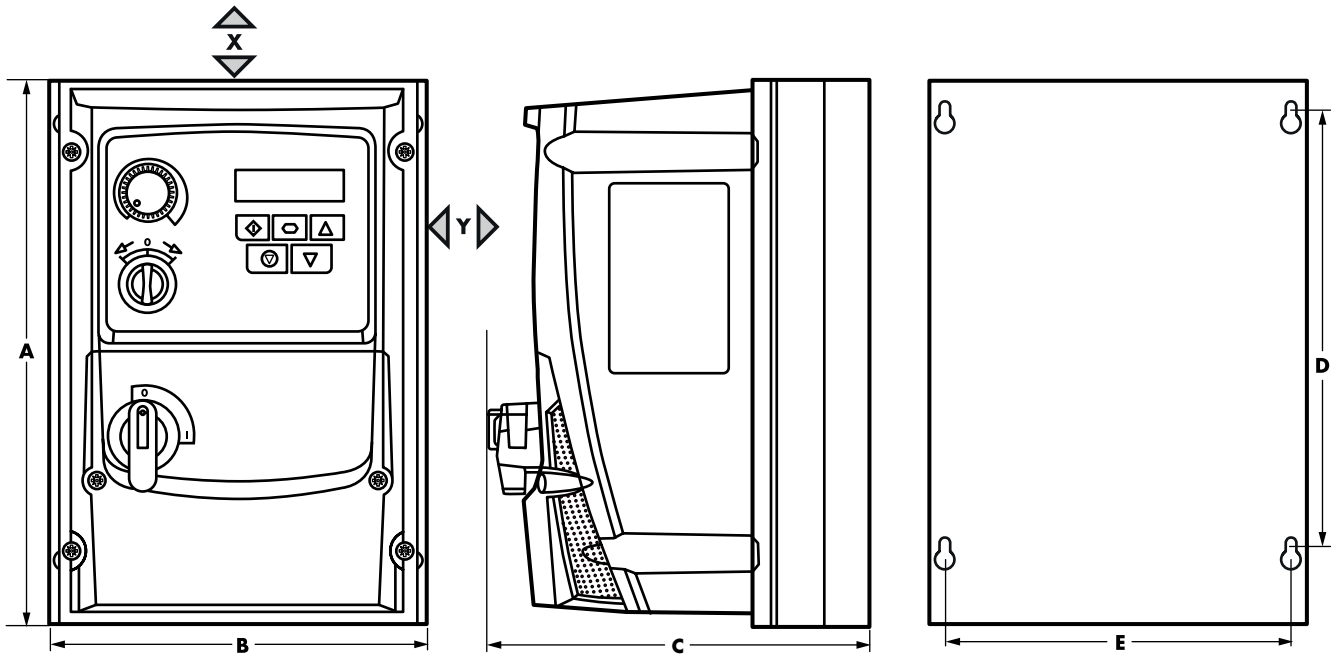
Prepare the Mounting Location

- The Optidrive must be mounted in a vertical position only.
- Installation should be on a suitable flat, flame resistant surface. Do not mount flammable material close to the drive.
- Refer to Technical Data and ensure the chosen mounting location is within the drive specification.
- The mounting location should be free from vibration.
- Do not mount the drive in any area with excessive humidity, corrosive airborne chemicals or potentially dangerous dust particles.
- Avoid mounting close to high heat sources.
- The drive must not be mounted in direct sunlight. If necessary, install a suitable shade cover.
- The mounting location must be free from frost.
- Do not restrict the flow of air through the drive heatsink. The drive generates heat which must be naturally allowed to dissipate. Correct air clearance around the drive must be observed.
- If the location is subject to wide ambient temperature and air pressure variation, install a suitable pressure compensation valve in the drive gland plate.

NOTE If the drive has been in storage for a period longer than 2 years, the DC link capacitors must be reformed. Refer to online documentation for further information.

3 MOUNT

Mechanical Dimensions



Dimensions

Drive Size	A		B		C		D		E		Weight	
	mm	in	mm	in	mm	in	mm	in	mm	in	kg	lb
1	232	9.13	161	6.34	162	6.37	189	7.44	148.5	5.85	2.5	5.5
2	257	10.12	188	7.4	182	7.16	200	7.87	176	6.93	3.5	7.7

Mounting Clearance

Drive Size	X Above & Below		Y Either Side	
	mm	in	mm	in
All Frame Sizes	200	7.87	10	0.39

NOTE

Typical drive heat losses are approximately 3% of operating load conditions. Above are guidelines only and the operating ambient temperature of the drive **MUST** be maintained at all times.

Mounting Bolts & Tightening Torques

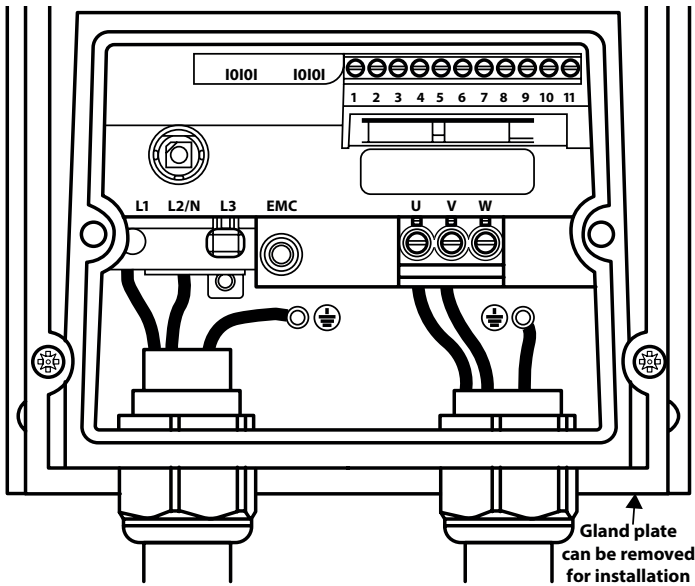
Mounting Bolts		Tightening Torques		
Frame Size		Frame Size	Control Terminals	Power Terminals
All Frame Sizes	4 x M4 (#8)	All Frame Sizes	0.8 Nm (7 lb-in)	1.5 Nm (13 lb-in)

4 CONNECT

Cable Selection

- The mains power cables should be connected to L1/L, L2/N.
- For compliance with CE and C Tick EMC requirements, refer to online documentation.
- A fixed installation is required according to IEC61800-5-1 with a suitable disconnecting device installed between the Optidrive and the AC Power Source. The disconnecting device must conform to the local safety code / regulations (e.g. within Europe, EN60204-1, Safety of machinery).
- The cables should be dimensioned according to any local codes or regulations. Maximum dimensions are given in the Rating Tables section of this Quick Start Guide.

Install the Wiring



Drive Size	Power & Motor Cables		
	Hole Size	Recommended PG Gland	Alternative Metric Gland
Size 1	22	PG 16	M20
Size 2	27	PG21	M25

Information for UL Compliance

Optidrive E3 is designed to meet the UL requirements. For an up to date list of UL compliant products, please refer to UL listing NMMS.E226333. In order to ensure full compliance, the following must be fully observed.

Input Power Supply Requirements				
Supply Voltage	200 – 240 RMS Volts for 230 Volt rated units, + / - 10% variation allowed. 240 Volt RMS Maximum.			
	380 – 480 Volts for 400 Volt rated units, + / - 10% variation allowed, Maximum 500 Volts RMS.			
Frequency	50 – 60Hz + / - 5% Variation			
Short Circuit Capacity	Voltage Rating	Min kW (HP)	Max kW (HP)	Maximum supply short-circuit current
	115v	0.37 (0.5)	0.75 (1)	100kA rms (AC)
	230v	0.37 (0.5)	11 (1.5)	100kA rms (AC)
All drives are suitable for use on a circuit capable of delivering not more than 100kA maximum short-circuit Amperes symmetrical with the specified maximum supply voltage when protected by Class J fuses.				
Mechanical Installation Requirements				
All Optidrive E3 units are intended for installation within controlled environments which meet the condition limits shown in the Environment section of this Quick Start Guide.				
The drive can be operated within an ambient temperature range as stated in the Environment section of this Quick Start Guide.				
For IP66 (Nema 4X) units, installation in a pollution degree 4 environment is permissible.				
Electrical Installation Requirements				
Incoming power supply connection must be according to the Install the Wiring section of this Quick Start Guide.				
Suitable power and motor cables should be selected according to the data shown in Rating Tables section of this Quick Start Guide and the National Electrical Code or other applicable local codes.				
Motor Cable	75°C Copper must be used.			
Power cable connections and tightening torques are shown in the Mechanical Dimensions section of this Quick Start Guide.				
Integral Solid State short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the national electrical code and any additional local codes. Ratings are shown in the Rating Tables section of this Quick Start Guide.				
UL Listed ring terminals / lugs must be used for all bus bar and grounding connections.				
General Requirements				
Optidrive E3 provides motor overload protection, set at 150% of full load, in accordance with the National Electrical Code (US). Where a motor thermistor is not fitted, or not utilised, Thermal Overload Memory Retention must be enabled by setting P-60 = 1. Where a motor thermistor is fitted and connected to the drive, connection must be carried out according to the information shown in the Motor Thermistor Connection section of the Quick Start Guide.				
UL rated ingress protection ("Type") is only met when cables are installed using a UL recognized bushing or fitting for a flexible conduit system which meets the required level of protection ("Type").				
For conduit installations the conduit entry holes require standard opening to the required sizes specified per the NEC.				
Not intended for installation using rigid conduit system.				
WARNING: The opening of the branch-circuit protective device may be an indication that a fault has been interrupted. To reduce the risk of fire or electric shock, current-carrying parts and other components of the controller should be examined and replaced if damaged. If burnout of the current element of an overload relay occurs, the complete overload relay must be replaced.				
ATTENTION: Le déclenchement du dispositif de protection du circuit de dérivation peut être dû à une coupure qui résulte d'un courant de défaut. Pour limiter le risque d'incendie ou de choc électrique, examiner les pièces porteuses de courant et les autres éléments du contrôleur et les remplacer s'ils sont endommagés. En cas de grillage de l'élément traversé par le courant dans un relais de surcharge, le relais tout entier doit être remplacé.				

Control Terminal Wiring

- All analog signal cables should be suitably shielded. Twisted pair cables are recommended.
- Power and Control Signal cables should be routed separately where possible, and must not be routed parallel to each other.
- Signal levels of different voltages e.g. 24 Volt DC and 110 Volt AC, should not be routed in the same cable.
- Maximum control terminal tightening torque is 0.5Nm.
- Control Cable entry conductor size: 0.05 – 2.5mm² / 30 – 12 AWG.

Control Terminal Connections

Switched Units: May use the built in control switch and potentiometer, or external control signals connected to the control terminals.

Non-Switched Units: Require external control signals to be connected to the control terminals.



6 POWER ON




7 COMMISSION

Operation

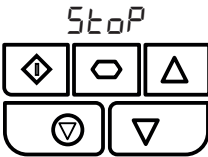
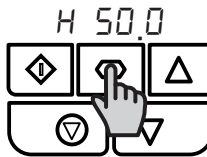
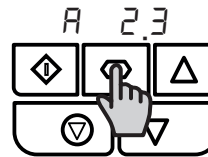
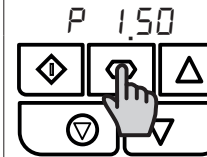
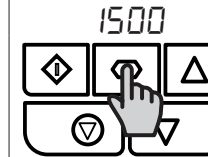
Managing the Keypad

The drive is configured and its operation monitored via the keypad and display.

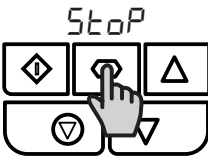
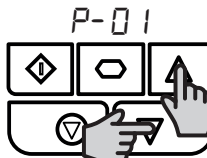
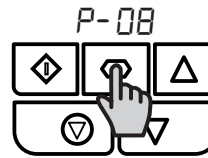
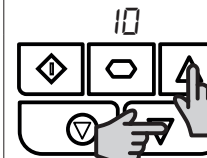
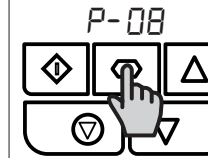
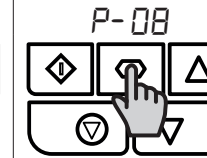
	START	When in keypad mode, used to Start a stopped drive or to reverse the direction of rotation if bi-directional keypad mode is enabled.
	UP	Used to increase speed in real-time mode or to increase parameter values in parameter edit mode.

	DOWN	Used to decrease speed in real-time mode or to decrease parameter values in parameter edit mode.
	NAVIGATE	Used to display real-time information, to access and exit parameter edit mode and to store parameter changes.
	RESET / STOP	Used to reset a tripped drive. When in Keypad mode is used to Stop a running drive.

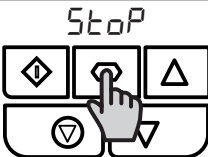
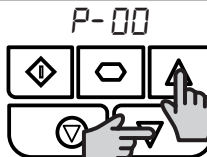
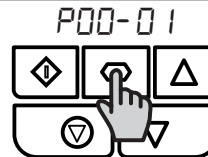
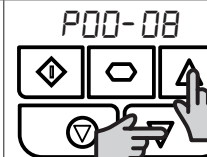
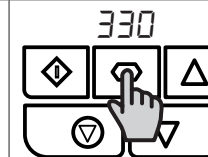
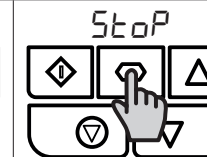
Operating Displays

				
Drive Stopped / Disabled	Drive is enabled / running, display shows the output frequency (Hz)	Press the Navigate key for < 1 second. The display will show the motor current (Amps)	Press the Navigate key for < 1 second. The display will show the motor power (kW)	If P-10 > 0, pressing the Navigate key for < 1 second will display the motor speed (RPM)

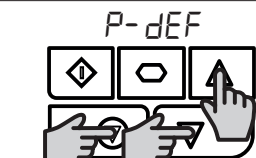
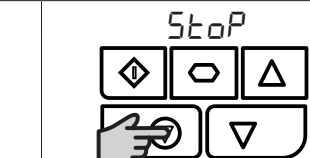
Changing Parameters

					
Press and hold the Navigate key > 2 seconds	Use the up and down keys to select the required parameter	Press the Navigate key for < 1 second	Adjust the value using the Up and Down keys	Press for < 1 second to return to the parameter menu	Press for > 2 seconds to return to the operating display

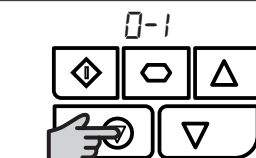
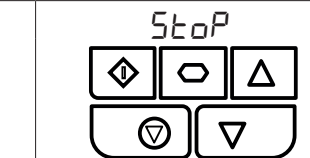
Read Only Parameter Access

					
Press and hold the Navigate key > 2 seconds	Use the up and down keys to select P-00	Press the Navigate key for < 1 second	Use the up and down keys to select the required Read Only parameter	Press the Navigate key for < 1 second to display the value	Press and hold the Navigate key > 2 seconds to return to the operating display

Resetting Parameters

	
To reset parameter values to their factory default settings, press and hold Up, Down and Stop buttons for > 2 seconds. The display will show "P-dEF"	Press the Stop key. The display will show "StoP"

Resetting a Fault

	
Press the Stop key. The display will show "StoP"	

Parameters

Standard Parameters

Par.	Description	Min	Max	Default	Units												
P-01	Maximum Frequency/Speed Limit	P-02	500.0	50.0 (60.0)	Hz/RPM												
P-02	Minimum Frequency/Speed Limit	0.0	P-01	0.0	Hz/RPM												
P-03	Acceleration Ramp Time	0.00	600.0	5.0	s												
P-04	Deceleration Ramp Time	0.00	600.0	5.0	s												
P-05	Stopping Mode/Mains Loss Response	0	2	1	-												
	<table border="1"> <thead> <tr> <th>Setting</th> <th>On Disable</th> <th>On Mains Loss</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Ramp to Stop (P-04)</td> <td>Ride Through (Recover energy from load to maintain operation)</td> </tr> <tr> <td>1</td> <td>Coast</td> <td>Coast</td> </tr> <tr> <td>2</td> <td>Ramp to Stop (P-04)</td> <td>Fast Ramp to Stop (P-24), Coast if P-24 = 0</td> </tr> </tbody> </table>	Setting	On Disable	On Mains Loss	0	Ramp to Stop (P-04)	Ride Through (Recover energy from load to maintain operation)	1	Coast	Coast	2	Ramp to Stop (P-04)	Fast Ramp to Stop (P-24), Coast if P-24 = 0				
Setting	On Disable	On Mains Loss															
0	Ramp to Stop (P-04)	Ride Through (Recover energy from load to maintain operation)															
1	Coast	Coast															
2	Ramp to Stop (P-04)	Fast Ramp to Stop (P-24), Coast if P-24 = 0															
P-07	Motor Rated Voltage	0	150/ 250	115/230	V												
P-08	Motor Rated Current	Drive Rating Dependent			A												
P-09	Motor Rated Frequency	25	500	50 (60)	Hz												
P-10	Motor Rated Speed	0	30000	0	RPM												
P-11	Start Boost Voltage	0.0	100.0	3.0	%												
P-12	Primary Command Source	0	9	0	-												
	0: Terminal Control 1: Uni-directional Keypad Control 2: Uni-directional Keypad Control 3: Modbus Network Control 4: Modbus Network Control 5: PI Control 6: PI Analog Summation Control 7: CAN Control 8: CAN Control 9: Slave Mode NOTE When P-12 = 1, 2, 3, 4, 7, 8 or 9, an enable signal must still be provided at the control terminals, digital input 1.																
P-14	Extended Menu Access code	0	65535	0	-												
	Enables access to Extended and Advanced Parameter Groups. This parameter must be set to the value programmed in P-37 (default: 101) to view and adjust Extended Parameters and value of P-37 + 100 to view and adjust Advanced Parameters. The code may be changed by the user in P-37 if desired.																

Extended Parameters

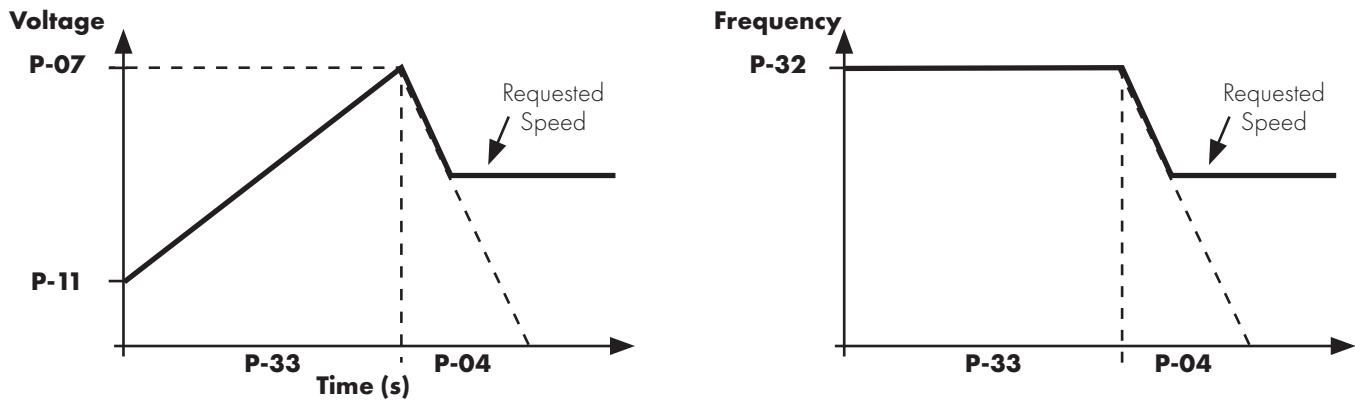
Par.	Description	Min	Max	Default	Units										
P-15	Digital Input Function Select	0	17	0	-										
P-16	Analog Input 1 Signal Format	See Below		U0-10	-										
	<table border="0"> <tr> <td>U 0-10 : Unidirectional, External 0 – 10Volt reference / pot</td> <td>E 20-4 : External 20 – 4mA signal, trip on loss</td> </tr> <tr> <td>b 0-10 : Bi-directional, External 0 – 10Volt reference / pot</td> <td>r 20-4 : External 20 – 4mA signal</td> </tr> <tr> <td>R 0-20 : External 0 – 20mA signal</td> <td>U 10-0 : External 10 – 0 Volt signal</td> </tr> <tr> <td>E 4-20 : External 4-20mA signal, trip on loss</td> <td>I n-Pot : Switched units only : Internal pot</td> </tr> <tr> <td>r 4-20 : External 4 – 20mA signal</td> <td></td> </tr> </table>					U 0-10 : Unidirectional, External 0 – 10Volt reference / pot	E 20-4 : External 20 – 4mA signal, trip on loss	b 0-10 : Bi-directional, External 0 – 10Volt reference / pot	r 20-4 : External 20 – 4mA signal	R 0-20 : External 0 – 20mA signal	U 10-0 : External 10 – 0 Volt signal	E 4-20 : External 4-20mA signal, trip on loss	I n-Pot : Switched units only : Internal pot	r 4-20 : External 4 – 20mA signal	
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r 4-20 : External 4 – 20mA signal															
P-18	Output Relay Function Select	0	9	1	-										
	<table border="0"> <tr> <td>0: Drive Enabled (Running)</td> <td>5: Output Current >= Limit</td> </tr> <tr> <td>1: Drive Healthy</td> <td>6: Output Frequency < Limit</td> </tr> <tr> <td>2: At Target Frequency (Speed)</td> <td>7: Output Current < Limit</td> </tr> <tr> <td>3: Drive Tripped</td> <td>8: Analog Input 2 > Limit</td> </tr> <tr> <td>4: Output Frequency >= Limit</td> <td>9: Drive Ready to Run</td> </tr> </table>					0: Drive Enabled (Running)	5: Output Current >= Limit	1: Drive Healthy	6: Output Frequency < Limit	2: At Target Frequency (Speed)	7: Output Current < Limit	3: Drive Tripped	8: Analog Input 2 > Limit	4: Output Frequency >= Limit	9: Drive Ready to Run
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4: Output Frequency >= Limit	9: Drive Ready to Run														
P-20	Preset Frequency / Speed 1	-P-01	P-01	5.0	Hz/RPM										
P-21	Preset Frequency / Speed 2	-P-01	P-01	25.0	Hz/RPM										
P-22	Preset Frequency / Speed 3	-P-01	P-01	40.0	Hz/RPM										
P-23	Preset Frequency / Speed 4	-P-01	P-01	P-09	Hz/RPM										
P-24	2nd Ramp Time (Fast Stop)	0.00	600.0	0.00	s										

Par.	Description	Min	Max	Default	Units
P-25	Analog Output Function Select	0	11	8	-
	Digital Output Mode. Logic 1 = +24V DC 0: Drive Enabled (Running) 1: Drive Healthy 2: At Target Frequency (Speed) 3: Drive Tripped 4: Output Frequency >= Limit 5: Output Current >= Limit 6: Output Frequency < Limit 7: Output Current < Limit	Analog Output Mode 8: Output Frequency (Motor Speed) 9: Output (Motor) Current 10: Output Power 11: Load Current			
P-30	Start/ Restart / Fire Mode Configuration				
	Index 1: Start Mode / Auto Restart	N/A		Edge-r	-
	<i>Edge-r</i> : Following Power on or reset, the drive will not start if Digital Input 1 remains closed. The Input must be closed after a power on or reset to start the drive. <i>Auto-r</i> : Following a Power On or Reset, the drive will automatically start if Digital Input 1 is closed. <i>Auto-r 1 To Auto-r 5</i> : Following a trip, the drive will make up to 5 attempts to restart at 20 second intervals.				
	Index 2: Fire Mode Input Logic	0	1	0	-
	0: Normally Closed (NC) input. Fire Mode active if input is open. 1: Normally Open (NO) input. Fire Mode active if input is closed.				
P-31	Index 3: Fire Mode Input Latch	0	1	0	-
	0: Latched input. The drive will remain in Fire Mode, only as long the fire mode input signal remains. 1: Momentary input. Fire Mode is activated by a momentary signal on the input. Normally Open or Normally Closed operation is supported depending on Index 2 setting.				
	Keypad Start Mode Select	0	7	1	-
0: Minimum Speed, Keypad Start 1: Previous Speed, Keypad Start 2: Minimum Speed, Terminal Enable 3: Previous Speed, Terminal Enable 4: Current Speed, Keypad Start 5: Preset Speed 4, Keypad Start 6: Current Speed, Terminal Start 7: Preset Speed 4, Terminal Start					
P-32	Starting Boost Frequency	0.0	P-09	P-09	Hz
Sets the frequency used during the starting boost phase of operation					
P-33	Boost Period Duration	0.0	150	5.0	s
Time for which the start-up boost period is applied. During this period, the output frequency is set to P-32 and the voltage increases linearly from P-11 to P-07. Setting P-33 to zero disables boost.					
P-34	Brake Chopper Enable (Not Size 1)	0	4	0	-
0: Disabled 1: Enabled With Software Protection 2: Enabled Without Software Protection 3: Enabled With Software Protection 4: Enabled Without Software Protection					
P-38	Parameter Access Lock	0	1	0	-
0: Unlocked 1: Locked					
P-39	Analog Input 1 Offset	-500.0	500.0	0.0	%
P-40	Index 1: Display Scaling Factor	0.000	16.000	0.000	-
	Index 2: Display Scaling Source	0	3	0	-
P-41	PI Controller Proportional Gain	0.0	30.0	1.0	-
P-42	PI Controller Integral Time	0.0	30.0	1.0	s
P-43	PI Controller Operating Mode	0	3	0	-
	0: Direct Operation 1: Inverse Operation 2: Direct Operation, Wake at Full Speed 3: Reverse Operation, Wake at Full Speed				
P-44	PI Reference (Setpoint) Source Select	0	1	0	-
	0: Digital Preset Setpoint 1: Analog Input 1 Setpoint				
P-45	PI Digital Setpoint	0.0	100.0	0.0	%

Par.	Description	Min	Max	Default	Units
P-46	PI Feedback Source Select	0	5	0	-
	0: Analog Input 2 1: Analog Input 1 2: Motor Current				
	3: DC Bus Voltage 4: Analog 1 – Analog 2 5: Largest (Analog 1, Analog 2)				
P-47	Analog Input 2 Signal Format	-	-	-	U0-10
	<i>U 0-10</i> : Unidirectional, External 0 – 10Volt reference / pot <i>R 0-20</i> : External 0 – 20mA signal <i>t 4-20</i> : External 4-20mA signal, trip on loss <i>r 4-20</i> : External 4 – 20mA signal				
	<i>t 20-4</i> : External 20 – 4mA signal, trip on loss <i>r 20-4</i> : External 20 – 4mA signal <i>Ptc-tc</i> : Motor thermistor				
P-48	Standby Mode Timer	0.0	25.0	0.0	s
P-49	PI Control Wake Up Error Level	0.0	100.0	5.0	%
P-50	User Output Relay Hysteresis	0.0	100.0	0.0	%

Single Phase Motor - Boost Starting cycle

In order to provide a reliable method for starting the motor, a special technique is used. The motor is started immediately at rated frequency, whilst the voltage is ramped from an initial Boost Voltage (set in P-11) to the Motor Rated Voltage (set in P-07) over a Boost Period Duration (set in P-33). Following the starting boost period, the drive then begins to control the output frequency and speed of the motor. The graphs below show how this operation works.



In order to achieve reliable starting and optimise the starting method, the following procedure can be used.

1. The motor must be correctly connected to the drive and safe to operate before using this procedure.
2. Ensure the motor rated voltage (P-07) and current (P-08) have been correctly programmed in the drive parameters.
3. Select Extended Parameter Access by setting P-14 = 101.
4. Set the Boost Period Duration P-33 to the maximum allowed value of 150 seconds.
5. Start the drive, and display the motor current (press the Navigate button until the display shows "R x.x" where x is the motor current).
6. Check the current value compared to the motor rated current around 3 – 5 seconds after starting the drive.
 - a. If the current displayed is less than 80% of the motor rated current:
 - o Stop the drive
 - o Increase P-11
 - o Repeat from step 5.
 - b. If the current displayed is greater than 90% of the motor rated current:
 - o Stop the drive
 - o Reduce P-11
 - o Repeat from step 5.
7. The correct boost voltage setting should deliver 80 – 90% of the motor rated current approximately 3 – 5 seconds after enabling the drive.
8. Now the Boost Period Duration may be reduced to match the actual time required for the motor to start. The simplest method is to initially reduce in large steps and monitor the motor behaviour on starting the drive. The ideal boost period will be a few seconds longer than is required to bring the motor to full speed.

By following this procedure, the motor starting parameter can be optimised to start the motor reliably without excessive starting current.

Technical Data

Environment

Operational ambient temperature range

Enclosed Drives: -20 ... 40°C (frost and condensation free)

Storage ambient temperature range: -40 ... 60°C

Maximum altitude: 2000m. Derate above 1000m: 1% / 100m

Maximum humidity: 95%, non-condensing

Rating Tables

Frame Size	kW	HP	Input Current	Fuse / MCB (Type B)		Maximum Cable Size		Output Current A	Recommended Brake Resistance Ω
				Non UL	UL	mm	AWG		
110 - 115 (+ / - 10%) V 1 Phase Input, 1 Phase Output									
1	0.37	0.5	8.5	16	15	8	8	7.0	-
2	0.75	1	12.5	16	15	8	8	10.5	100
200 - 240 (+ / - 10%) V 3 Phase Input, 3 Phase Output									
1	0.37	0.5	6.0	10	10	8	8	4.3	-
1	0.75	1	9.3	16	15	8	8	7.0	-
1	1.1	1.5	14.0	20	20	8	8	10.5	100

NOTE Cable sizes shown are the maximum possible that may be connected to the drive. Cables should be selected according to local wiring codes or regulations at the point of installation.

Troubleshooting

Fault Code Messages

Fault Code	No.	Description
<i>O1-b</i>	01	Brake channel over current
<i>OL-br</i>	02	Brake resistor overload
<i>O-I</i>	03	Output Over Current
<i>I_{th}-trP</i>	04	Motor Thermal Overload (I _{2t})
<i>O-volt</i>	06	Over voltage on DC bus
<i>U-volt</i>	07	Under voltage on DC bus
<i>O-t</i>	08	Heatsink over temperature
<i>U-t</i>	09	Under temperature
<i>E-tr iP</i>	11	External trip
<i>SC-ObS</i>	12	Optibus comms loss
<i>FLt-dc</i>	13	DC bus ripple too high
<i>P-LOSS</i>	14	Input phase loss trip
<i>h O-I</i>	15	Output Over Current
<i>th-FLt</i>	16	Faulty thermistor on heatsink
<i>dAtA-F</i>	17	Internal memory fault (IO)
<i>4-20 F</i>	18	4-20mA Signal Lost
<i>dAtA-E</i>	19	Internal memory fault (DSP)
<i>F-Ptc</i>	21	Motor PTC thermistor trip
<i>FAn-F</i>	22	Cooling Fan Fault (IP66 only)
<i>O-hEAt</i>	23	Drive internal temperature too high
<i>OUt-F</i>	26	Output Fault
<i>AtF-O2</i>	41	Autotune Fault
<i>SC-FD1</i>	50	Modbus comms loss fault
<i>SC-FD2</i>	51	CAN comms loss trip

NOTE Following an over current or overload trip (1, 3, 4, 15), the drive may not be reset until the reset time delay has elapsed to prevent damage to the drive.



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